

# Low-cost sensors for the measurement of atmospheric composition.

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Based on:

Lewis, Peltier and von Schneidmesser, WMO, 2018

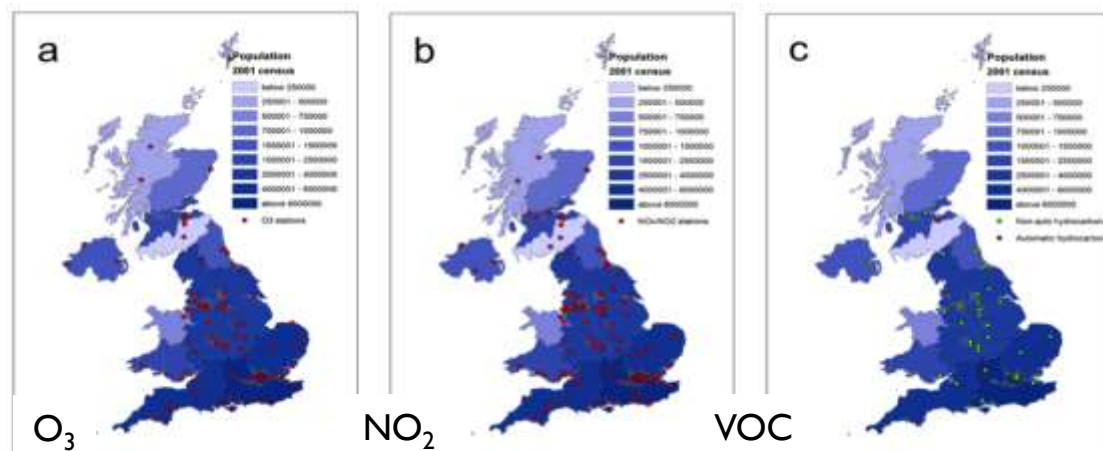
Lewis et al., *Faraday Discussions*. **189**, 85-103, 2016

Smith et al. *Faraday Discussions*. **200**, 621-637, 2017.

Pang et al. *Sensor and Actuators B*, **240**, 753-766, 2017.

Lewis and Edwards, *Nature*, **535**, 29-31, 2016

# Sensors – improving on the observational gaps?



- UK as an example: approximately 140 static measurement sites.
- One static monitoring site per 250,000 population



- Many new commercial products aimed at personal exposure monitoring.
- Professional applications include exposure / health science
- Amateur user applications include behaviour change, public interest, campaigning groups.



# Rapidly changing commercial landscape



# The challenge of component and system diversity

- The rate of change of sub-components can be rapid
- Past studies don't necessarily represent current capability
- The data quality from one sensor may differ from a network of sensors
- *There is far more to 'cost' than just buying the equipment*



Metal oxide  
~ £5  
~ since 1960s



Electrochemical  
/ voltammetric  
~ £50  
~ since 1980's



Photochemical  
~ £200  
~ since 1990's



Micro-optical  
> £100  
~ since 2000's

Sensor



Micro-electro-mechanical  
(MEMS) device

sensor

/ˈsɛnsə/ ⓘ

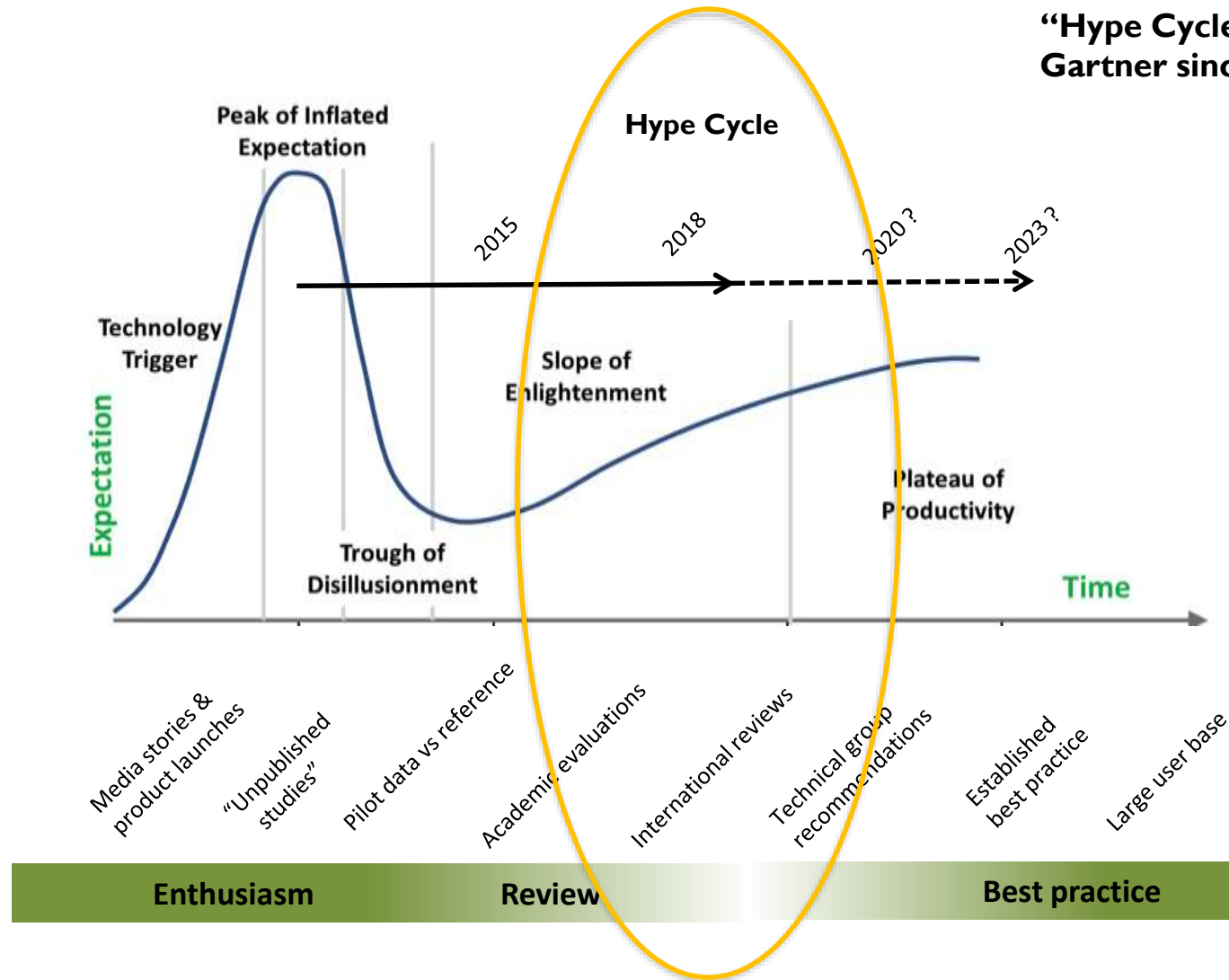
*noun*  
noun: sensor; plural noun: sensors

a device which detects or measures a physical property and records, indicates, or otherwise responds to it.

*Sensors have many other positive attributes beyond unit cost*

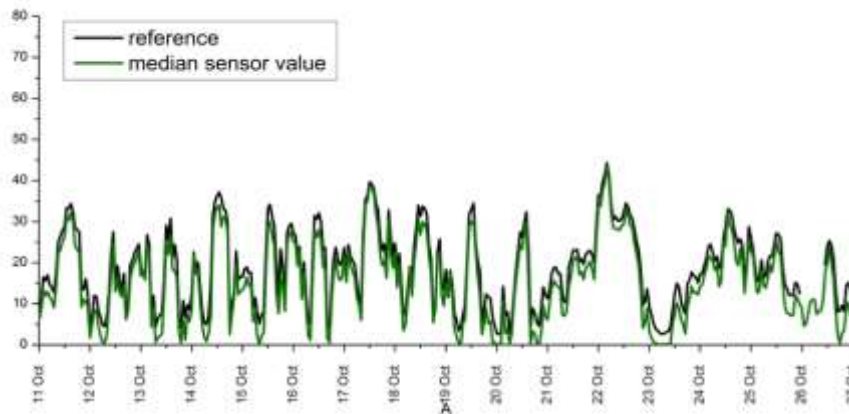
# Where are we now?

“Hype Cycle” model used by Gartner since 1995





# 2014-2018 –increase in “evaluation and advice”

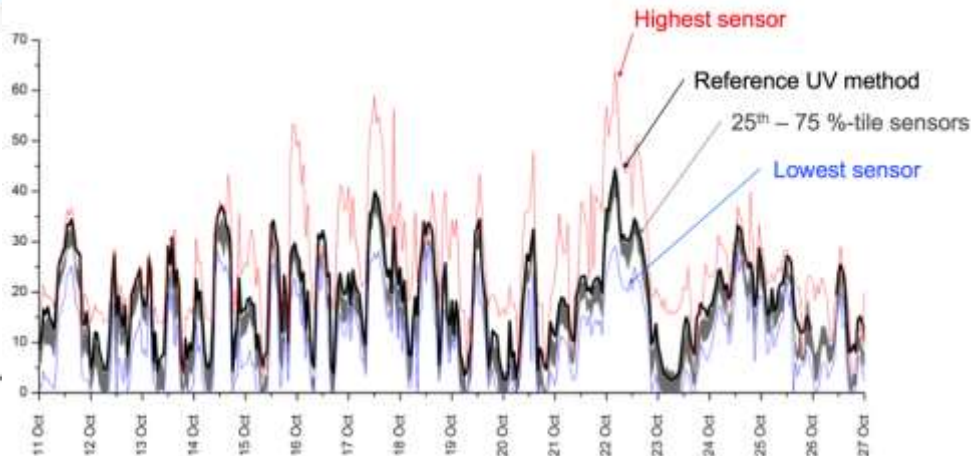


- Side by side comparison has been the main metric.
- Many positive examples of correlations next to reference monitors.
- Increasing use of training data and machine learning against reference



Low-cost sensors for the measurement of atmospheric composition: overview of topic and future applications  
valid as of May 2018

Editors: Alexander C. Lewis, Erika van Veenendaal and Richard P. Weber



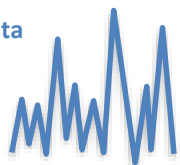
- True ‘blind’ inter-comparisons can be less good.
- Inter-sensor variability is less well defined – heavy tuning to the ‘best sensor’
- Very few annual or longer studies or performance



# Applications and data requirements

- Not an exclusive list of applications, but these are some that have been proposed by WMO
- General requirements in terms of sensor performance differ by application

Sensor data

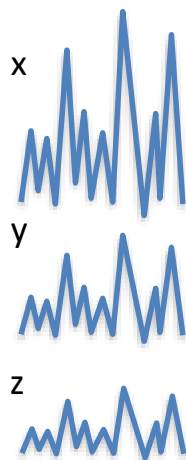


## Temporal variability

*e.g. 'Pollution is highest in the morning'*

Minimum requirements:

1. Sensors are stable over the period of interest
2. Sensors respond broadly to the pollution parameter

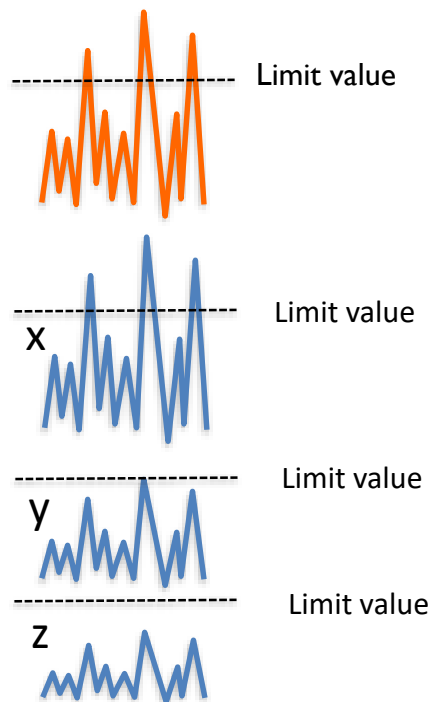


## Spatial variability

*e.g. 'location x has higher air pollution than locations y and z'*

1. Stable over the period of interest
2. Responds broadly to pollution parameter
3. Sensors are internally reproducible

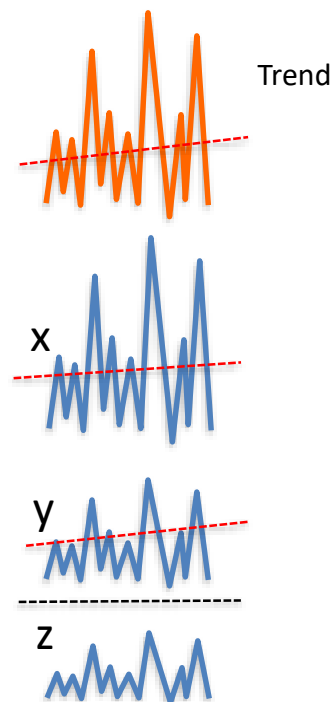
Reference site data



## Concentration dependence

*e.g. 'location x exceeds the AQ limits but y and z do not'*

1. Stable over the period of interest
2. Sensors are compound specific
3. Sensors are externally reproducible

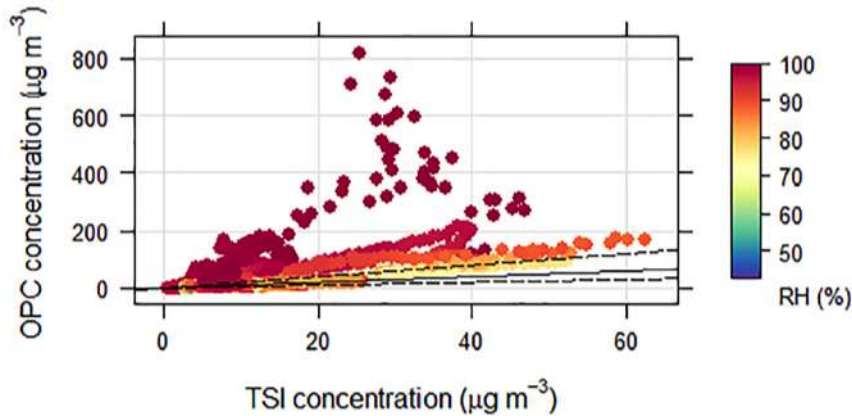


## Long-term trends

*e.g. 'species at location x is increasing at 3% yr'*

1. Stable over the period of interest
2. Sensors are compound specific
3. Sensors are globally intercomparable

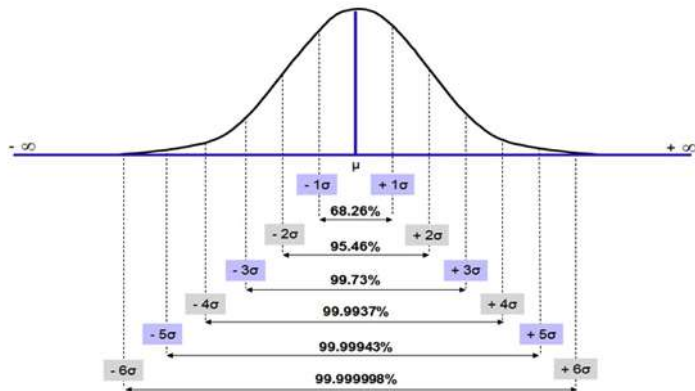
# Some of the key issues identified



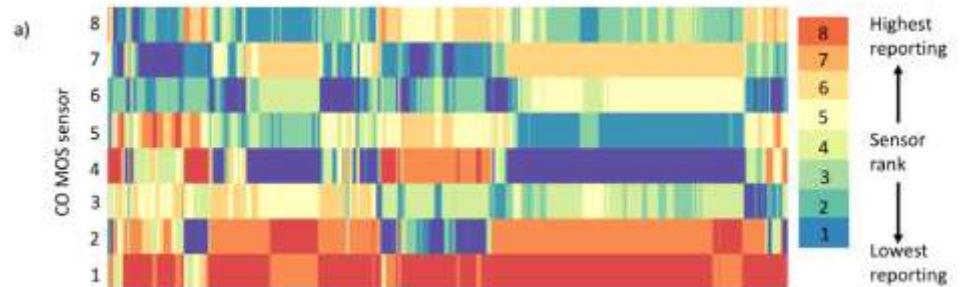
Sensitivity to meteorology and environment

Sensor	Compound					Co-pollutants		
	CO	SO <sub>2</sub>	NO	O <sub>3</sub>	NO <sub>2</sub>	CO <sub>2</sub>	H <sub>2</sub>	%RH*
CO - B4	0.378	-0.013	0.000	0.0200	0.032	0.000	-0.032	0.201
OX-B421	0.000	-0.016	-0.110	0.439	0.44	$9.5 \times 10^{-5}$		0.560
SO <sub>2</sub> -B4	0.013	0.210	0.023	-0.014	-0.32	$9.8 \times 10^{-6}$		0.000
NO-B4	0	0.007	0.558	-0.011	-0.590	$1.8 \times 10^{-5}$		-0.303
NO <sub>2</sub> -B4	0	0.004	-0.008	0	0.148	$2.3 \times 10^{-5}$		0.000

Sensitivity to other air pollutants (interferences)



Sensor to sensor variability



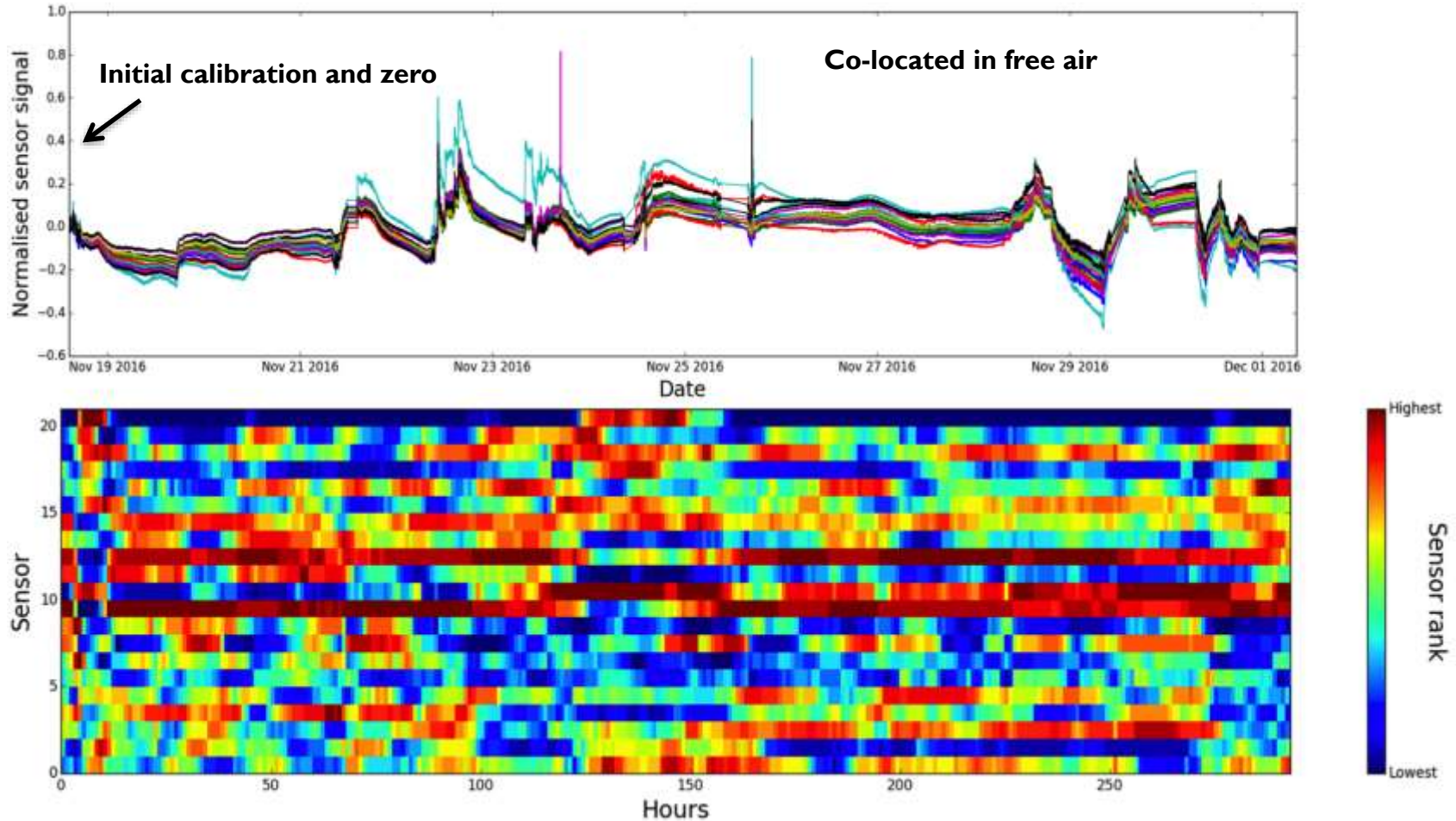
Long-term performance and change

- Data processing strategies are proposed to potentially correct for some or all of these data quality factors notably “Machine Learning” in its many different forms.



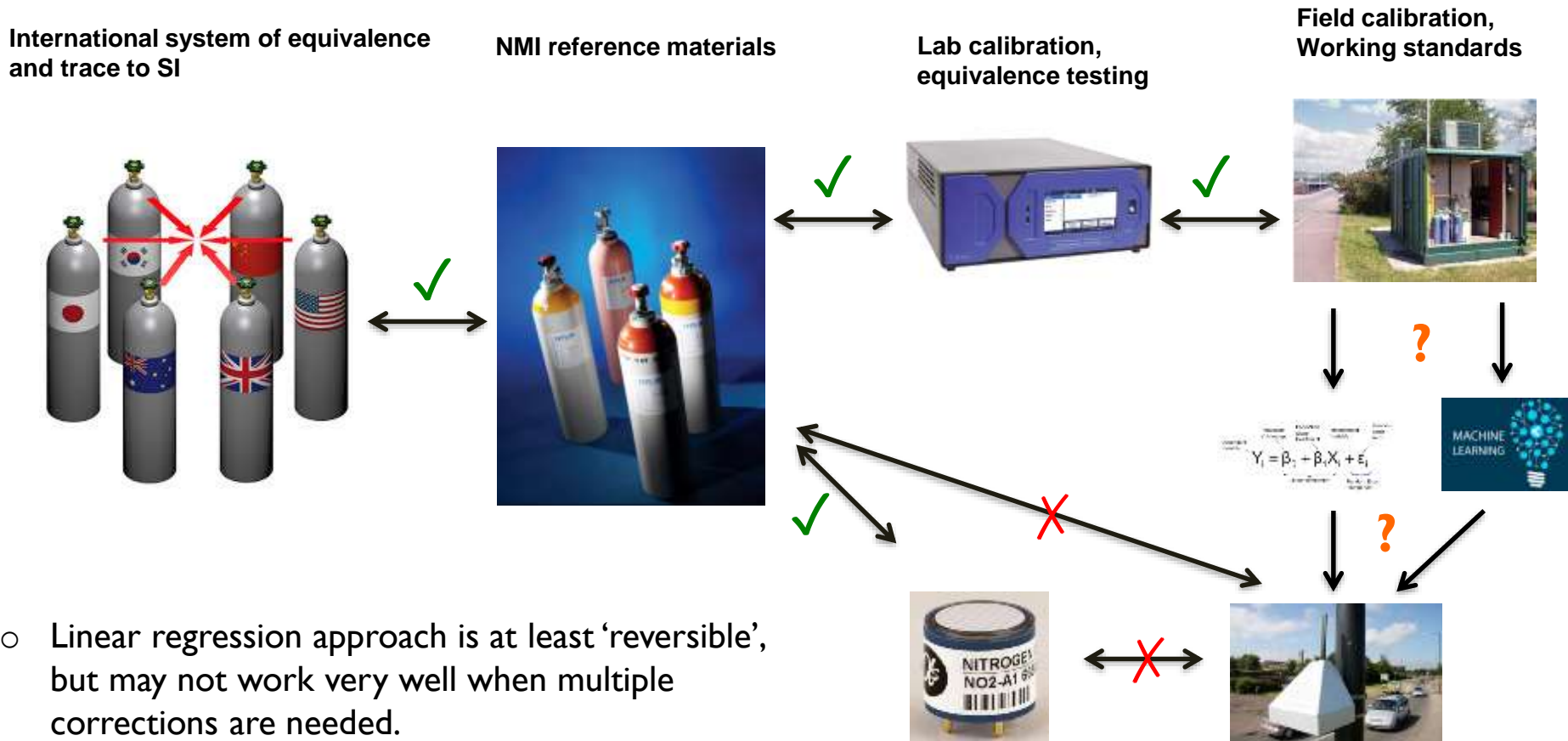
# Understanding sensor variability

- Sensors are 'predictably unpredictable', but there is often collective skill
- 20 identical MOS sensors, with temperature and humidity controlled
- Ranking the sensors from the highest responding to lowest



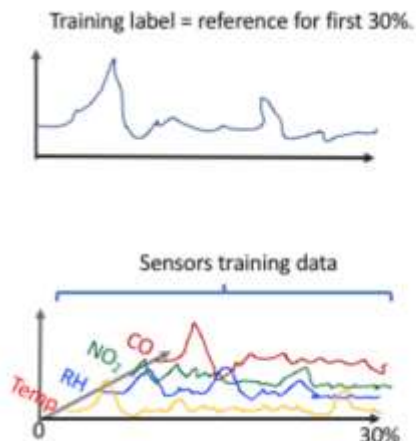
# Sensor traceability challenges

- There is a well established global system for equivalence and traceability based on binary and multi-component gas standards.
- The high sensitivity of sensors to environmental conditions, water vapour, chemical cross-interferences makes existing system incompatible

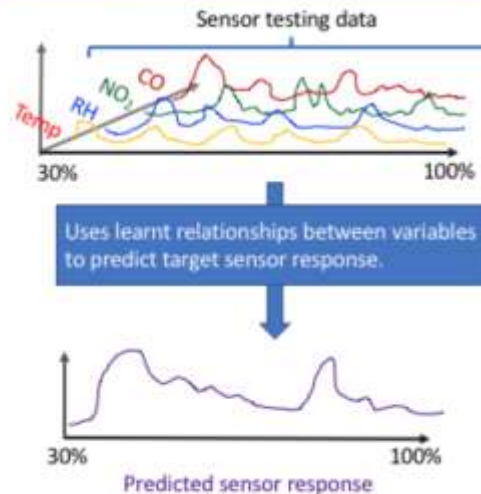


# Data correction techniques and AQ sensors

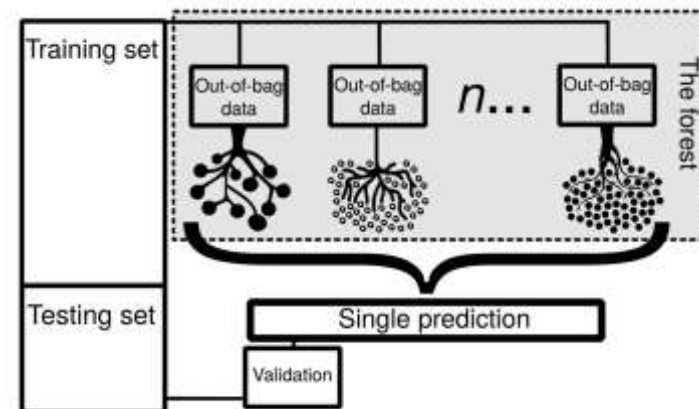
During training : machine learning algorithm identifies relationships between the all sensor box variables and also with the training label for the compound of interest.



During testing : machine learning algorithm uses the learnt relationships between the all sensor box variables to predict a sensor response for the compound of interest.

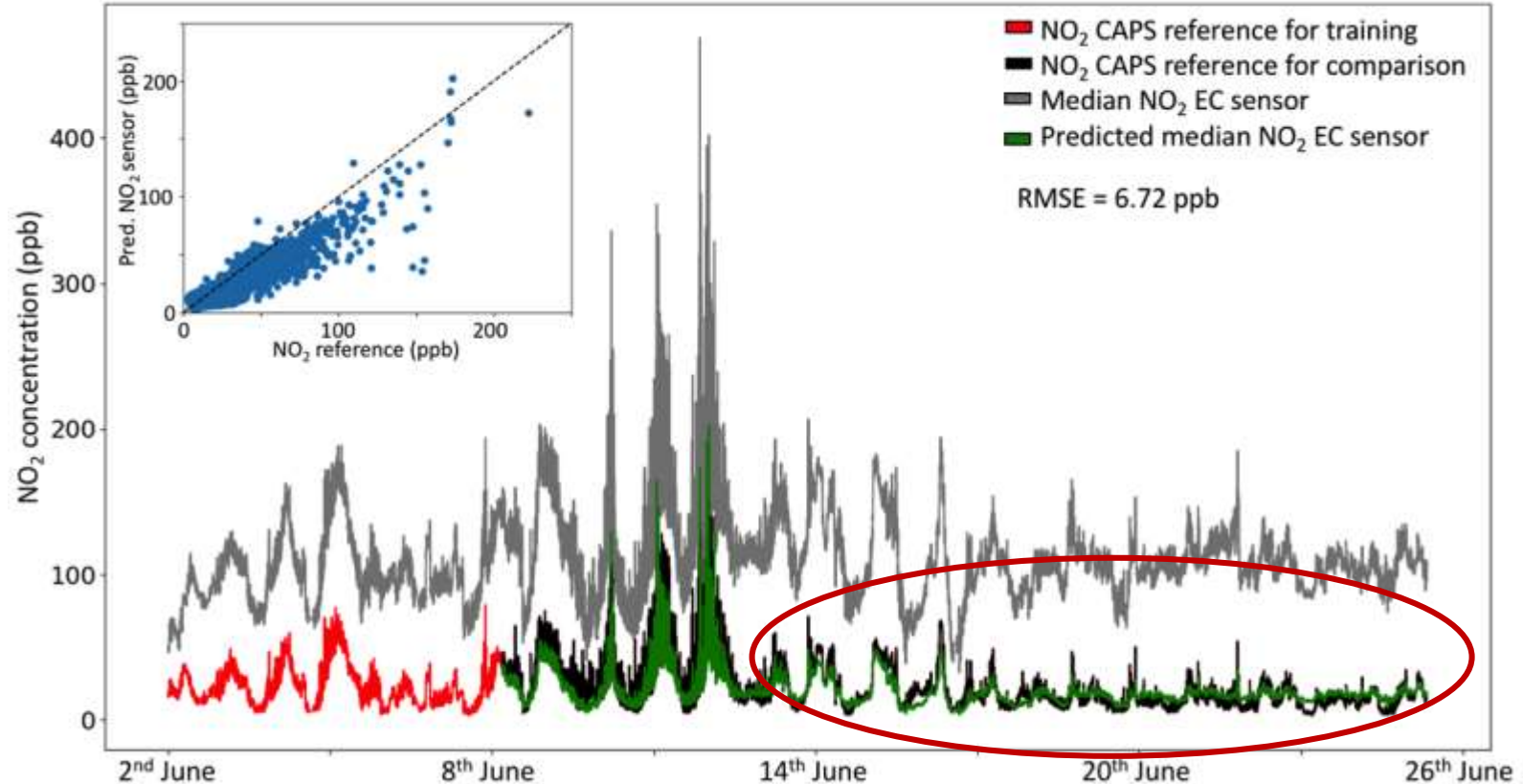


- ML can learn how an AQ sensor responds compared to a reference instrument, and then uses this to then improve the prediction for an unknown period.
- Needs to learn from co-measured data on the key interference parameters eg Temp, RH, windspeed, CO<sub>2</sub>, other pollutants
- Boosted regression trees are one ML method that is 'transparent'.



Boosted regression trees

# Boosted linear regression

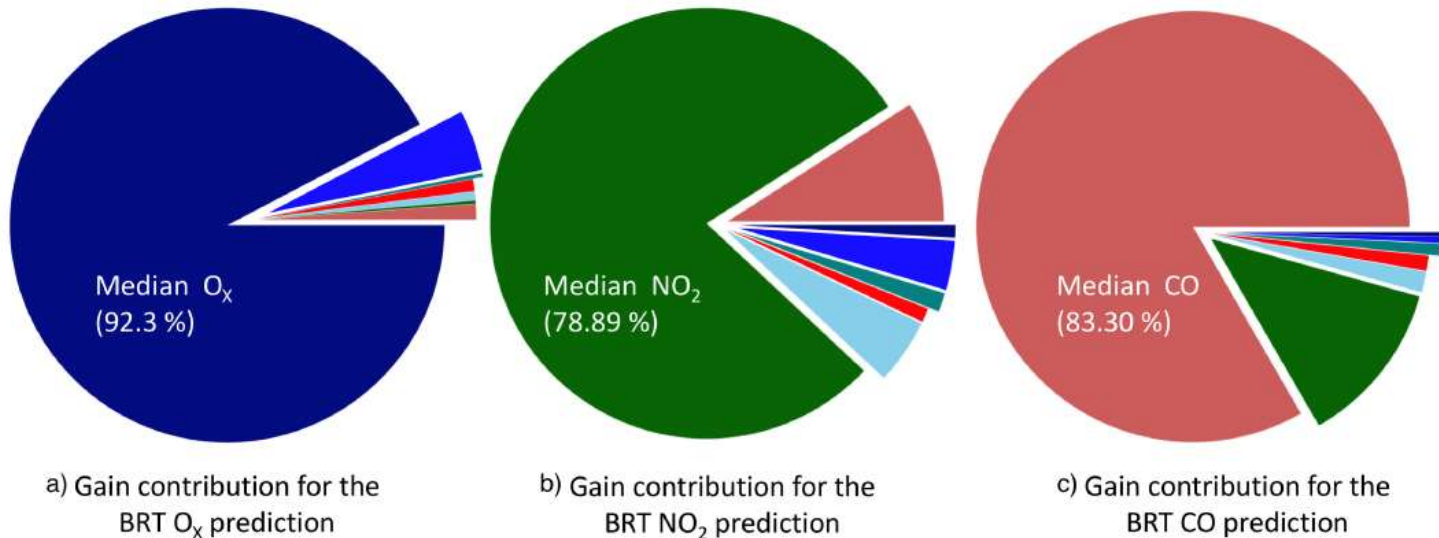


- Using a week of reference data (in red) for NO<sub>2</sub>, plus all other parameters, eg T, RH, CO, O<sub>3</sub>, M etc for 'learning', then apply boosted linear regression to the green period.
- The ML method then produces sensor data that agrees better for NO<sub>2</sub> under more 'normal conditions'.



## Measurement vs model?

- Needs very careful supervision. It is possible to 'predict' a sensor value, even with no sensor present.
- Machine learning can make a very good guess of concentrations, just by learning how reference data responses to: time of day, days of week, weather and some other pollutants concentrations. **This is not a measurement!**
- Restricted to T, RH, VOC, CO, O<sub>x</sub> etc for 'learning',



Key:

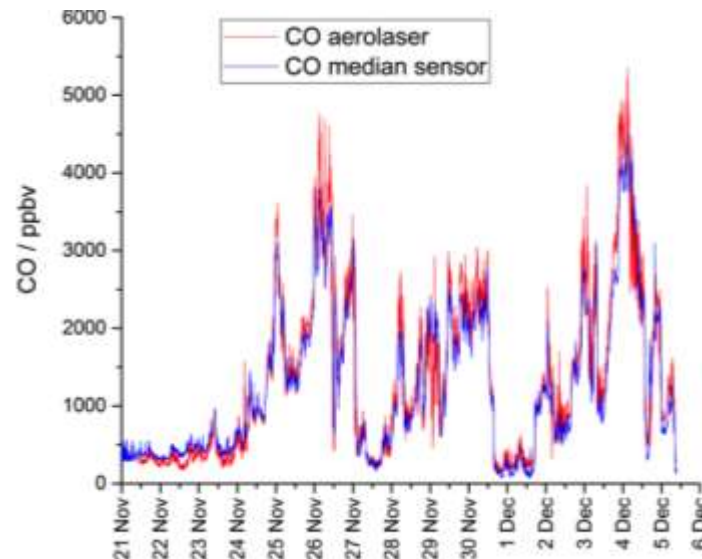
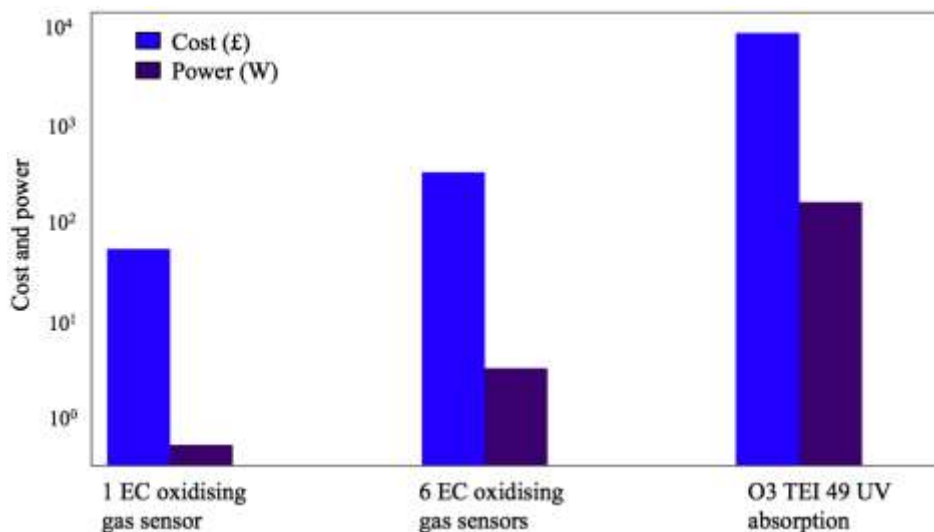
- Median O<sub>x</sub> (ppb)
- Median NO<sub>2</sub> (ppb)
- Median CO (ppb)
- Median VOC (V)
- Median O<sub>3</sub> ( Med. O<sub>x</sub> – Med. NO<sub>2</sub>) (ppb)
- Relative humidity (%)
- Temperature (°C)

Machine Learning data source contributions used to predict final sensor value



## Have we missed the point of sensors?

- We are trying to make a huge technology jump in one step:
  1. Massively reducing initial hardware cost, **AND**
  2. Making devices portable / externally deployable) **AND**
  3. Inventing a new calibration paradigm, **AND**
  4. Reducing operational burden of measurement
- A next step *may* be to tackle only one to two of these problems at a time:



- Hardware cost is still low whether you buy one sensor, or 6, or 20.
- The biggest gain, from a operational perspective, is **low electrical power and fewer expensive high energy parts.**
- One sensor is rather poor, but the median of a cluster is much better.

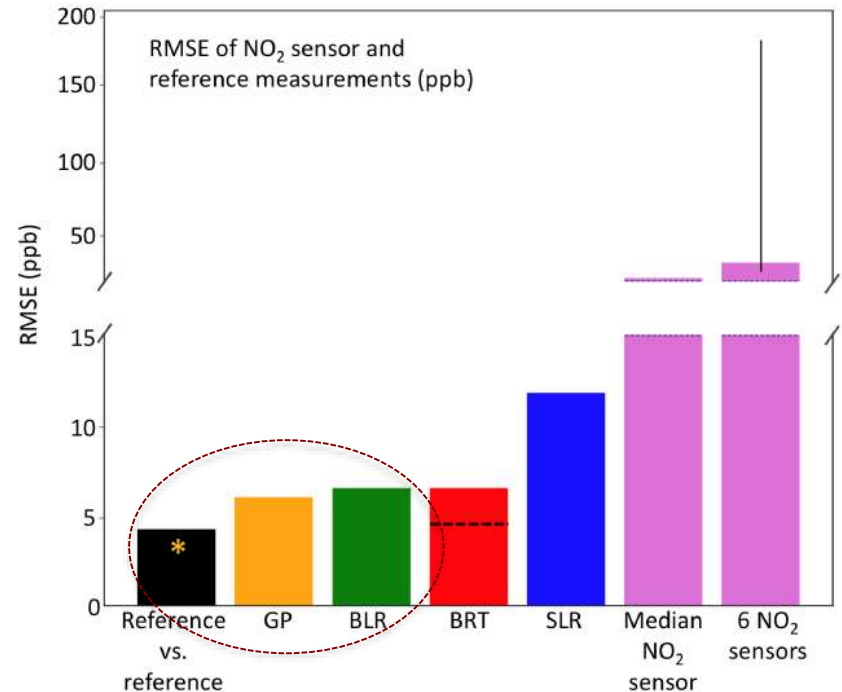
## Using AQ sensors to make reference grade measurements

- Clusters of six identical sensors for each pollutant (48 sensors total)
- Use median value from the cluster for each parameter
- Make corrections using simultaneous T, RH, flow, CO<sub>2</sub> data.



**AQ cluster: 6x (CO, O<sub>3</sub>, NO, NO<sub>2</sub>, VOC, CO<sub>2</sub>) + T, P RH**

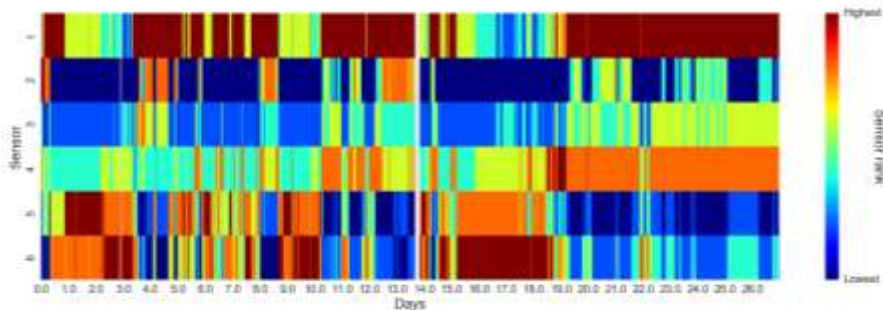
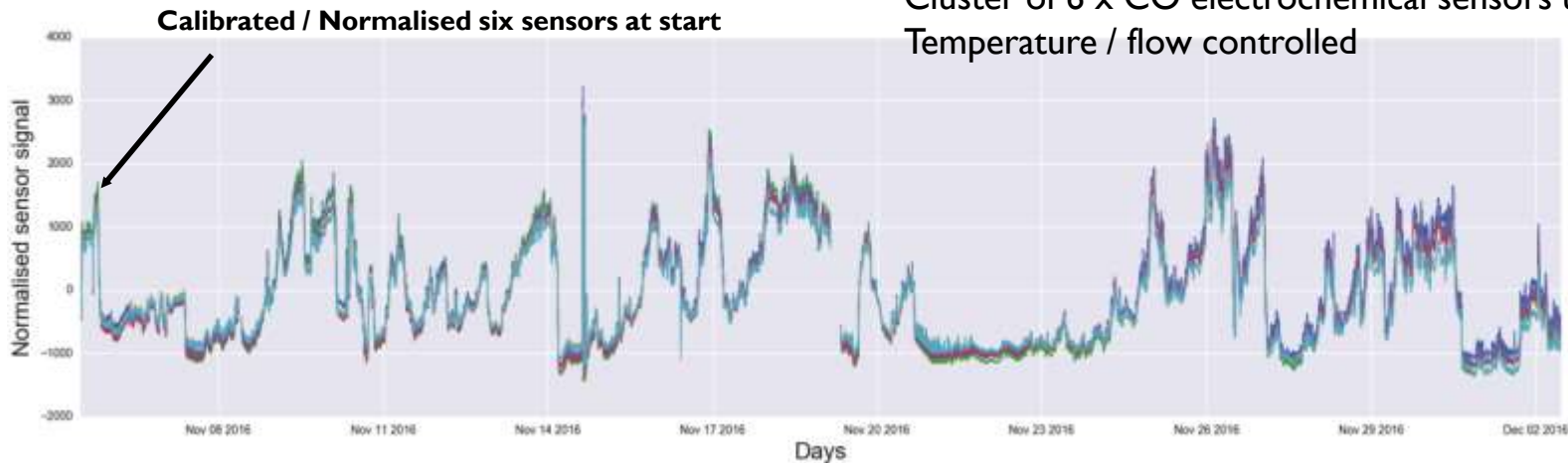
- Measuring multiple simultaneous parameters and using sensor cluster median values + ML, produces data very close regulatory standard.
- Power ~100W, cost ~10,000 USD, weight 10 kg.



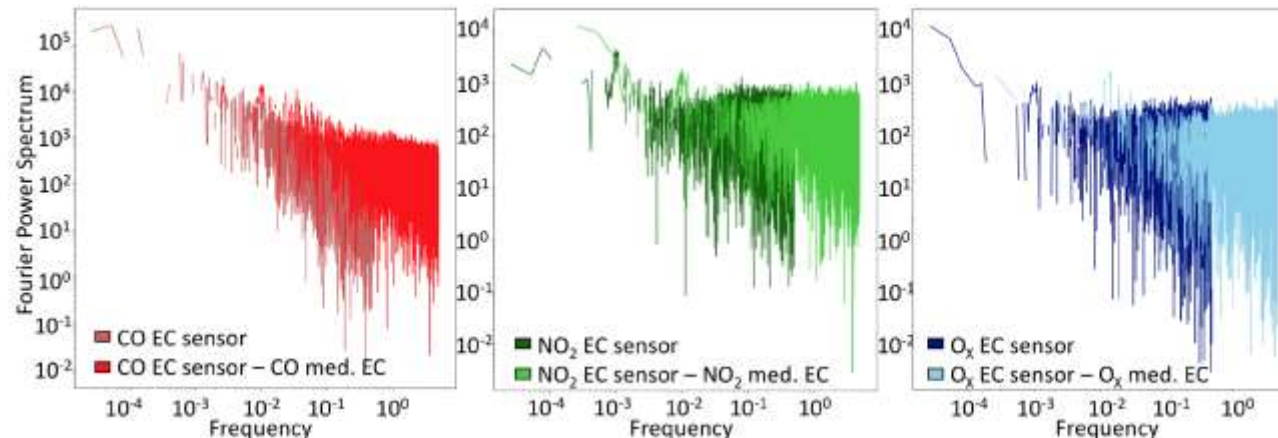
**RMSE using clusters + ML methods vs reference instrument**

# How clusters of sensors help

Cluster of 6 x CO electrochemical sensors used in Beijing  
Temperature / flow controlled



- Randomised day-to-day drift is the biggest source of error
- Using a the cluster median value resolves this over week-to month timescales.



Subtracting the median value generates white noise, vs pink noise for individual sensors

# Conclusions

- Current off-the-shelf AQ sensor devices are **highly variable**.
  - Some **market attrition** of the poorest quality already; survival of the fittest.
  - **Publication bias** with limited reports on uncertainties in the real-world
  - **Chemical cross-interferences do occur** at low concentrations,
  - **Environmental interferences** can require very large corrections
  - Randomised response drifts over the **hour to day timescale** are large compared to instantaneous sensitivity (which is often very good).
- 
- Operating under **stable** 'lab' conditions gives better results than placing uncontrolled outdoors – obvious.
  - **Clusters of sensors** can solve single-sensor drift problems, but maintain many important operational advantages, like power, size, costs.
  - **Statistical methods** offer considerable promise for removing interferences
  - But too much reliance on ML can mean it is simply a model prediction, not a measurement
  - Think more about **incremental steps** with sensors, rather than immediately solving all cost/autonomy/power/calibration challenges in one step?